



JET Simulations, Experiments and Theories

Numerical Simulations in MHD. Tools and Methods

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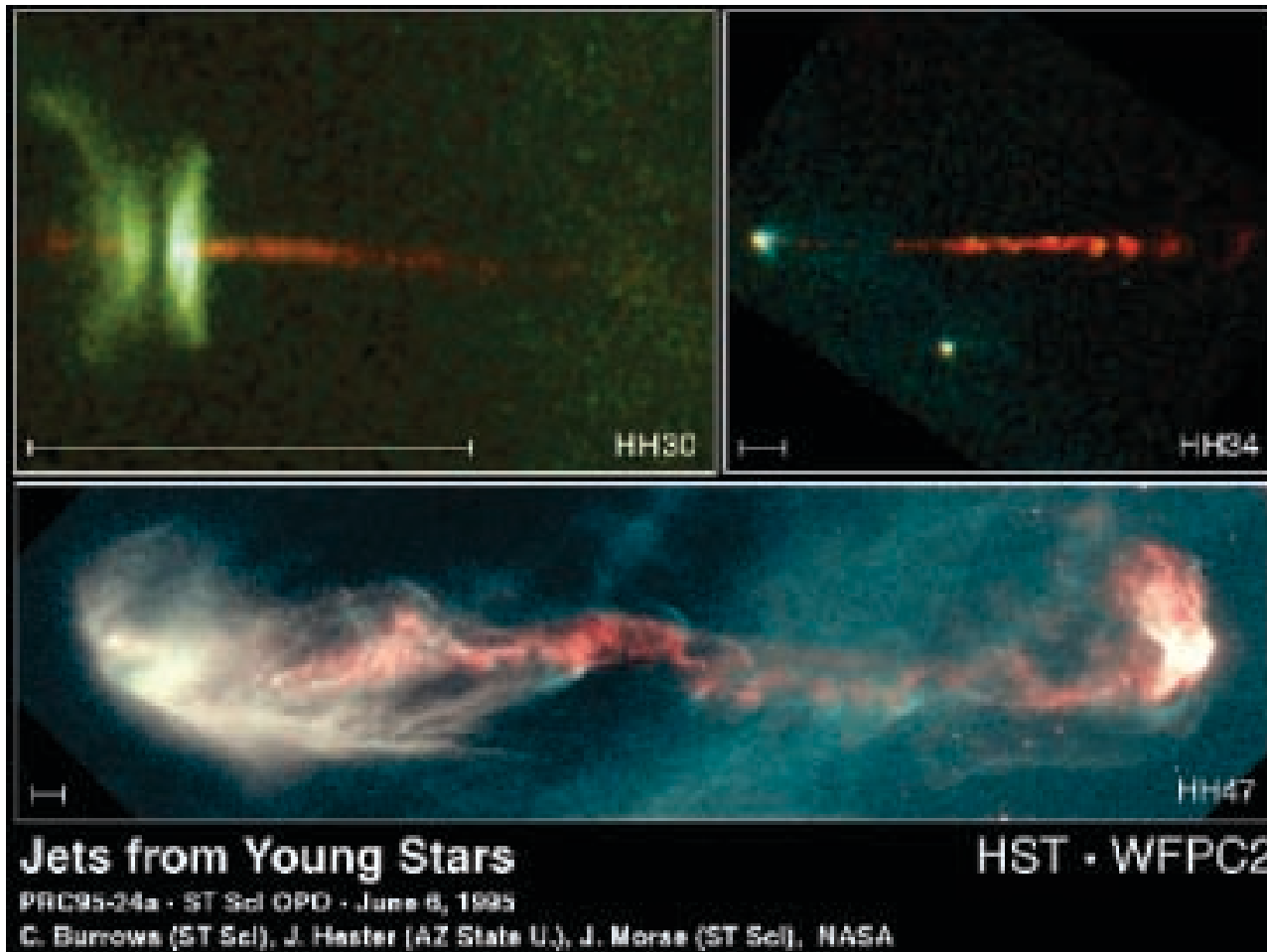
www.jetsets.org



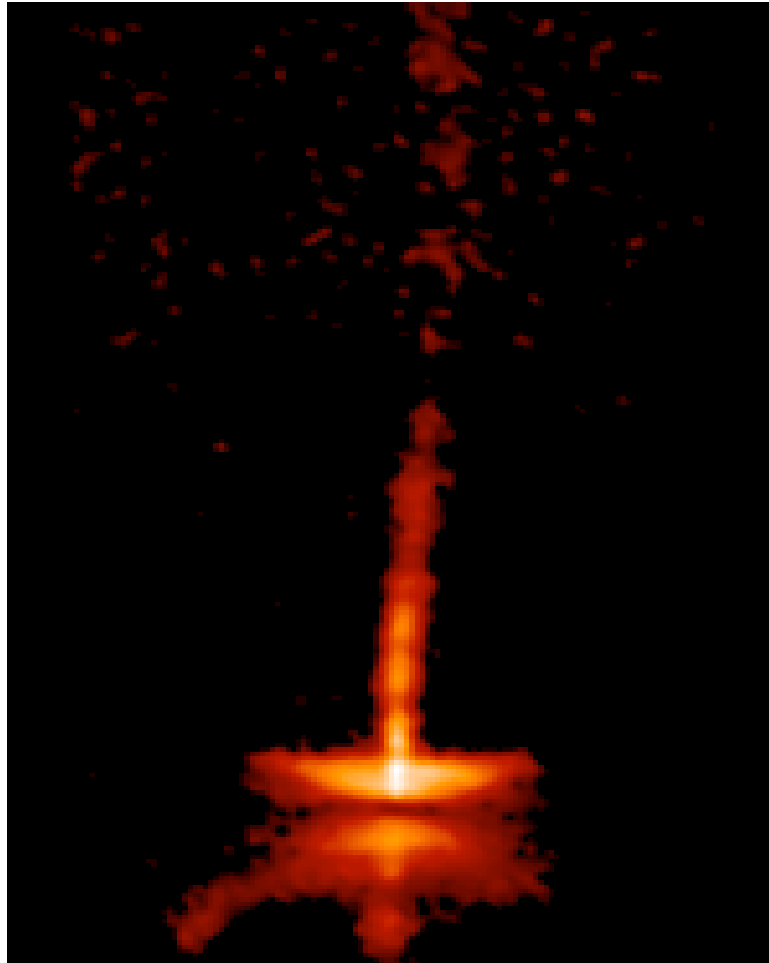
- **Introduction**
- **Methods**
- **Tools**
- **Prospects**

- **Astrophysical media**
 - multicomponent?, large gradients
 - viscosity, resistivity
 - chemistry?
- **Analytical solutions and their limitations**
 - “exact” solutions
 - analytical approximations
- **Art of numerical simulations**
 - numerical approximations
 - setup, choice of B.C. and I.C.

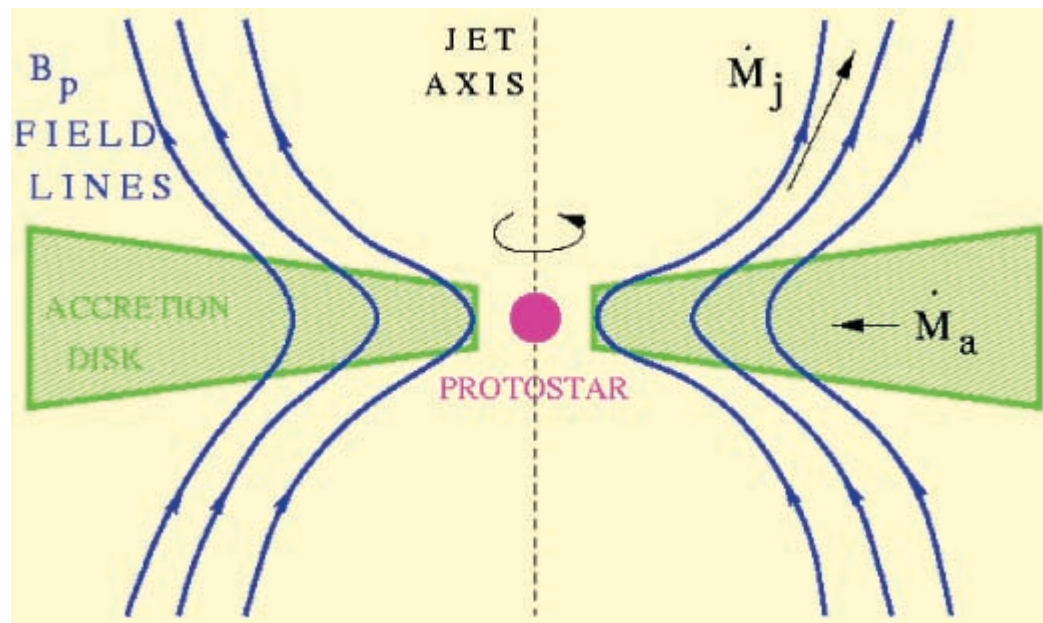
- Observations – young stellar objects



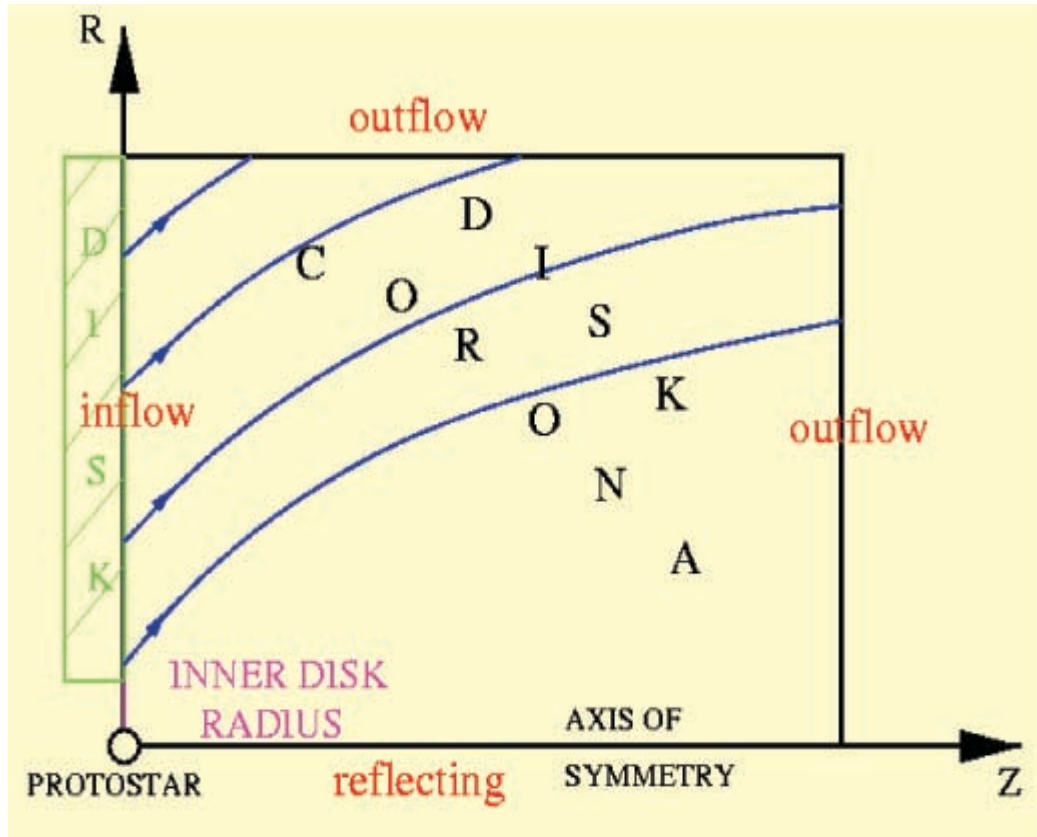
- More precise observations – HH30 1995-2000



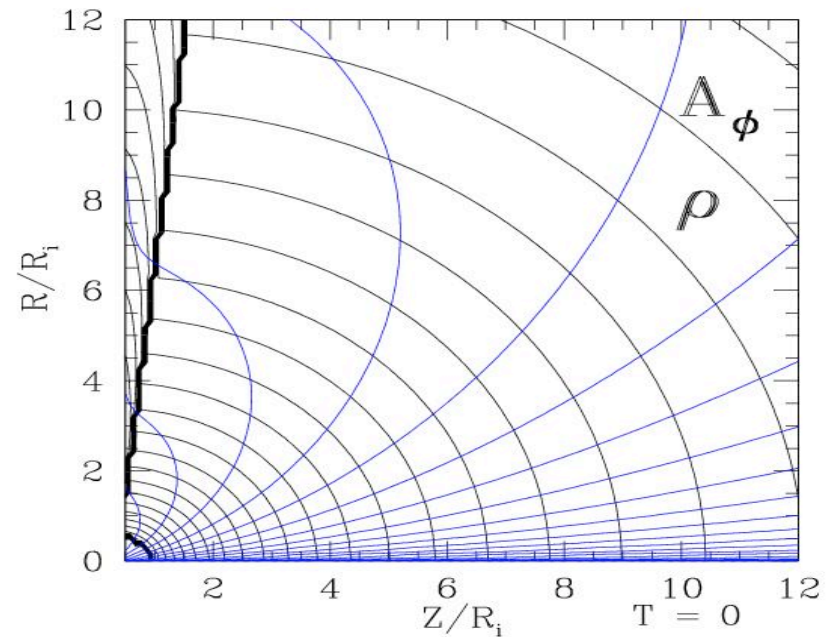
- Example: Sketch of the model



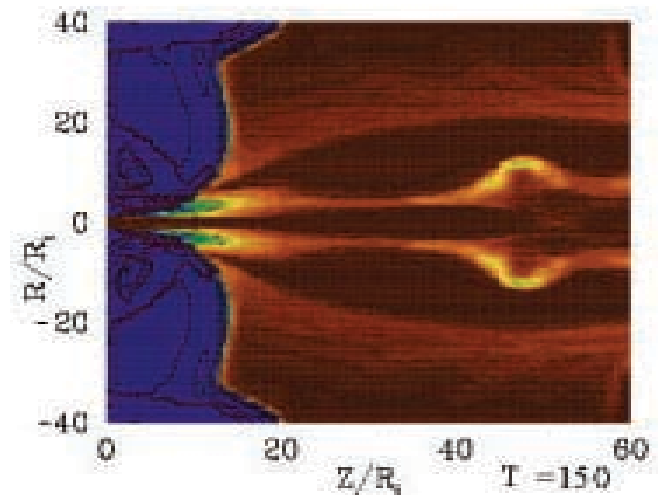
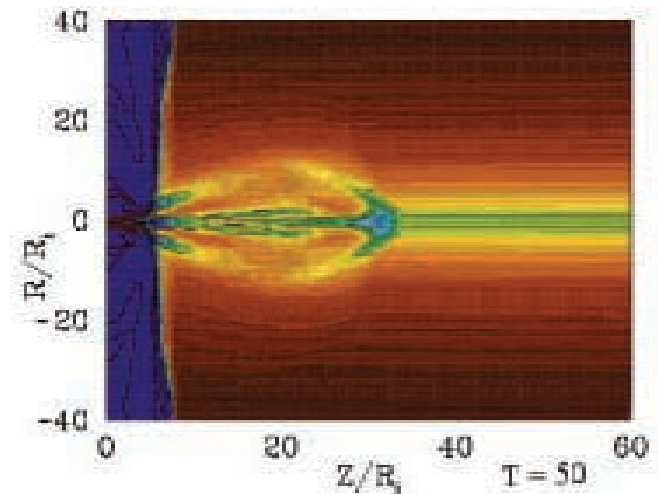
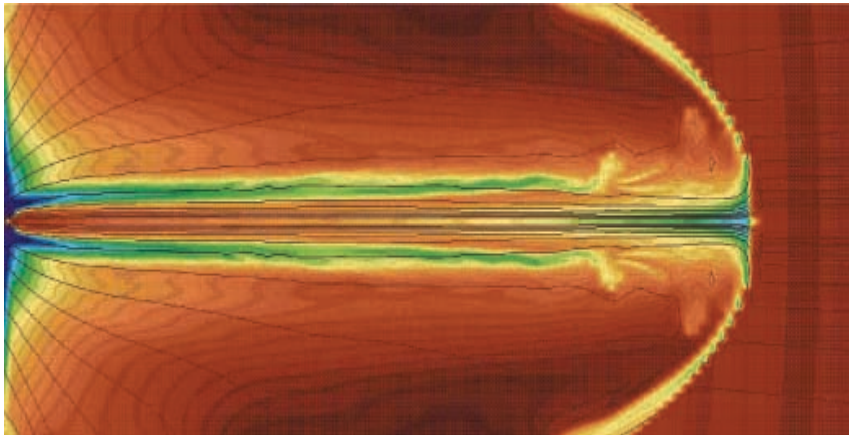
- Setup of the jet without disk included in the comp. box



- Setup of the jet with the disk included in the comp. box



- Quasistationary states



- ZEUS-3D
- ZEUS-MP

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{u}) = 0$$

$$\rho \left[\frac{\partial \mathbf{u}}{\partial t} + (\mathbf{u} \cdot \nabla) \mathbf{u} \right] + \nabla p - \rho \nabla \left(\frac{GM}{\sqrt{r^2 + z^2}} \right) - \frac{\mathbf{j} \times \mathbf{B}}{c} = 0$$

$$\frac{\partial \mathbf{B}}{\partial t} - \nabla \times \left(\mathbf{u} \times \mathbf{B} - \frac{c \mathbf{j}}{\sigma} \right) = 0$$

$$\rho \left[\frac{\partial e}{\partial t} + (\mathbf{u} \cdot \nabla) e \right] + p(\nabla \cdot \mathbf{u}) - \frac{\mathbf{j}^2}{\sigma} = 0$$

$$\nabla \cdot \mathbf{B} = 0$$

$$\frac{4\pi}{c} \mathbf{j} = \nabla \times \mathbf{B}$$

$$p = K \rho^\gamma, \quad e = \frac{p}{\gamma - 1}, \quad \gamma = \frac{5}{3}$$

$$\frac{\partial \mathbf{B}}{\partial t} = \nabla \times (\mathbf{u} \times \mathbf{B}) + \eta \nabla^2 \mathbf{B}, \quad \eta = \frac{c^2}{4\pi\sigma}$$

- **The set of differential equations for:**
 - ρ (density)
 - ρu (momentum)
 - ρe (energy)
 - B (magnetic field)
 - p (pressure)
- **Numerical schemes (discretizations)**
 - differ in addressing the contact and shock discontinuities in the flow
 - overall accuracy depends on the way these problems are solved
 - finite differences, finite volume and finite elements method

- Use of neighbouring points: approximation of the derivative of an unknown quantity U at a grid point by the ratio of the difference in U at two adjacent points to the distance between the grid points.
 - mostly on regular mesh

- The variables are approximated by their average values in each volume, and the changes through the surfaces of each volume are approximated as a function of the variables in neighbouring volumes.
 - on both regular and irregular mesh

- Also splits up the spaces into small pieces (called *elements*) as in finite volume method. But now a grid point exchanges the information with all the other grid points with which it shares an element.
 - no advantage of regular mesh
- All this possible in AMR (adaptive mesh refinement) approach

- **Classical**

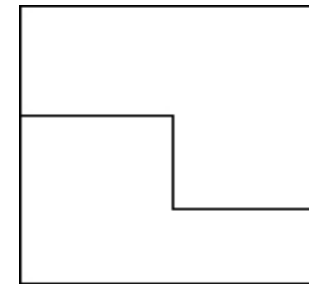
- linear numerical dissipation terms
- the same dissipation at all grid points
- for smooth and weak-shock solutions
- symmetric or central discretization
- no info used about wave propagation

- **and modern method**

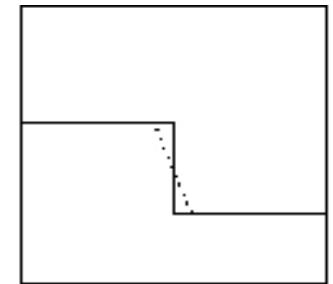
- non-linear numerical dissipation
- feedback for adjusting of dissipation
- every cell adjusted
- based on “upwind differences” (PDEs solutions dependent on velocity sign)

- **intermediate method**

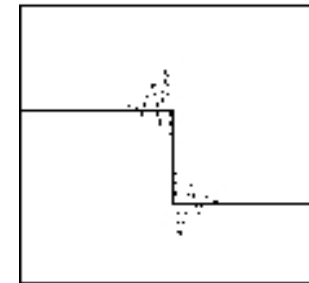
- linear numerical dissipation terms, non-linear switch functions



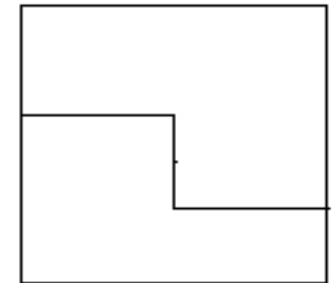
analytical solution



First-order Method



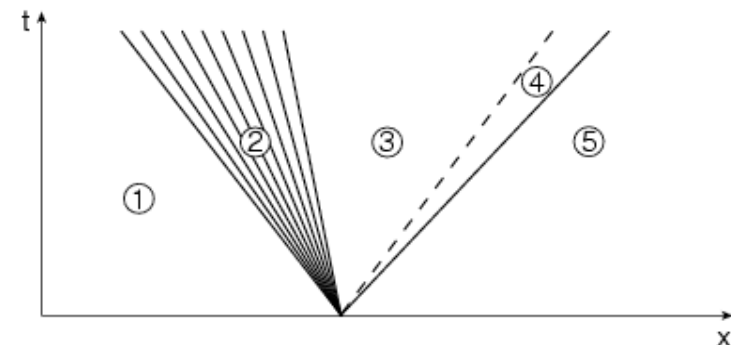
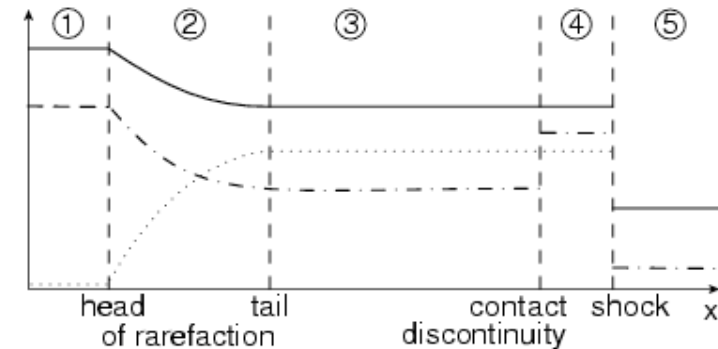
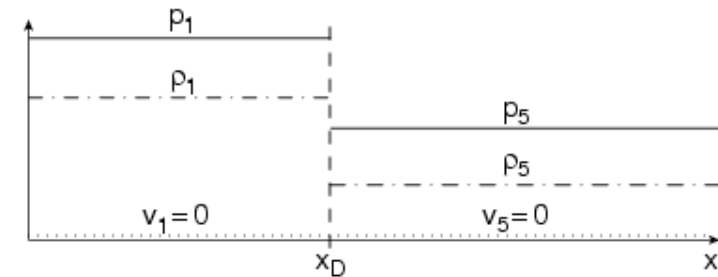
Second-Order Method



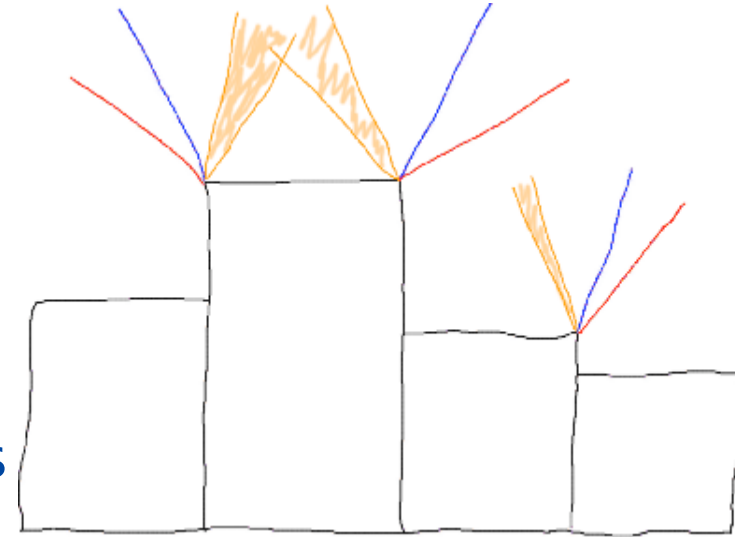
Shock-Capturing Method

FIG. 2. *Examples of numerical discretizations*

- The simplest initial value problem
 - discontinuous data
 - two separated constant states
 - breakup of discontinuity
 - two types of waves:
 - shocks *and* rarefactions
 - contact discontinuity (moving)



- **Godunov (1959) exact Riemann solver**
 - solving of a separate Riemann problems
 - solving at each cell boundary
- **Three steps ($U=1, v, e$):**
 - reconstruction of $\rho U(x)$ from cell ρU -es
 - solving of Riemann problems for Δt
 - computing the fluxes across cell boundaries and averaging of $\rho U(x)$ -es to obtain ρU -es
- ***Useful method, but in original form too diffusive***



- What is usually used is combination of Godunov's concept with high-order reconstruction (solution averaging):
 - Van Leer (1979): MUSCL (Monotone Upwind Schemes for Scalar Conservation Laws)-linear reconstruction: approximation of piecewise-linear Riemann problems by piecewise-constant Riemann problems including slope-limiter, solution of the Lagrange equations and Eulerian remapping.
 - Colella & Woodward (1984): PPM (Piecewise Parabolic Method): piecewise parabolic reconstruction via primitive functions, contact steepening.
 - Approximate (linearized) Riemann solvers may serve as well in splitting the flow into waves with different characteristic velocities and upwind directions.

- **(Approximate) Riemann solvers account for upwinding and shock capturing but:**
 - involved computations, costly in CPU time
- **Alternatives-simpler-make use of:**
 - von Neumann-Richtmyer viscosity
 - Runge-Kutta steps
 - operator-splitting of advection and pressure terms
- **Other Riemann solvers:**
 - Approximate Riemann Solver of Roe (1981)-solves exactly a linearised problem (by an algorithm by Roe), instead of looking for an iterative solution of the exact original Riemann problem
 - Harten-Lax-van Leer-Einfeldt (or HLLE) scheme (1988)-the energy of a flow is highly kinetic

- **Directional (dimensional) splitting**
 - applying the operator splitting to the spatial derivatives in Euler eqs.

$$\frac{\partial}{\partial t} \mathbf{q} + \frac{\partial}{\partial x} \mathbf{F}(\mathbf{q}) + \frac{\partial}{\partial y} \mathbf{F}(\mathbf{q}) = \mathbf{0}$$

$$q_{X,i}^{n,*} = q_i^n - \frac{\Delta t}{\Delta x} \left(f\left(q_{i+\frac{1}{2}}^n\right) - f\left(q_{i-\frac{1}{2}}^n\right) \right)$$

$$q_{X+Y,i}^{n+1} = q_{X,i}^{n,*} - \frac{\Delta t}{\Delta y} \left(f\left(q_{X,i+\frac{1}{2}}^{n,*}\right) - f\left(q_{X,i-\frac{1}{2}}^{n,*}\right) \right) .$$

Machines

- “Deep Thought” (ref.:Douglas Adams “The Hitchhiker's Guide to the Galaxy”) or shared computing (your work/home desktop? Laptop?)
- dedicated cluster
- Grid technology

In Athens

- Linux machines
- MS Windows machines
- Cluster(s)
- Buying NOW with REAL money: Dual Core, AMD Athlon X2, 4400, 4GB RAM, Operating System: Scientific Linux 4.2 (Kernel 2.6.9).



Dedicated packages or Big-General-Ultra-Mega-Giga-Hyper-code or even specially designed machine?

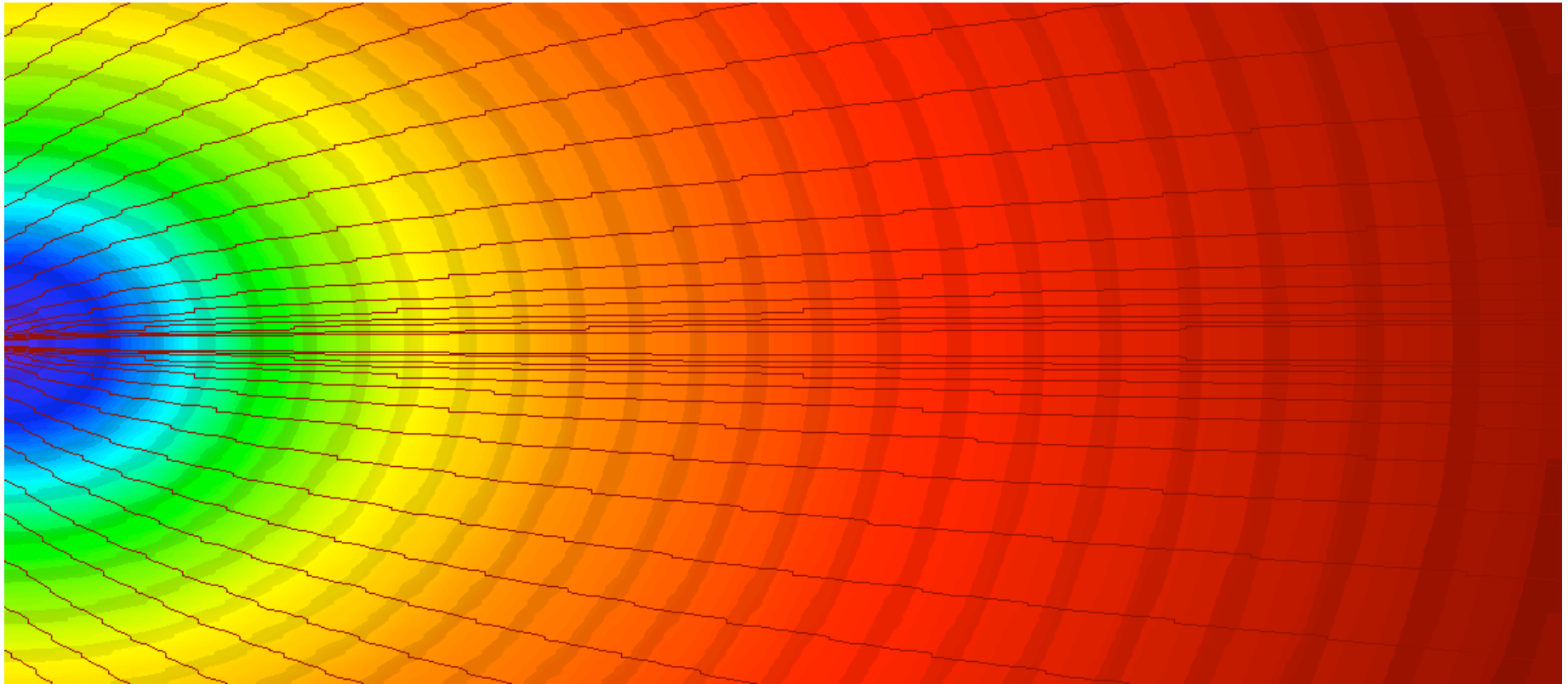
- Codes part 1
 - ZEUS (ZEUS3D) [LCA, NCSA David Clarke, Michael Norman, Robert Fiedler] MHD 3D + Molecular
 - 3DAthena-NASA [Stephen O'Sullivan] MHD 3D
 - AMRAthena (Zeus Team) [Tom Gardiner] MHD 3D
 - AMRVAC [Rony Keppens] MHD 3D
 - AMRAstroBear [Adam Frank + Peguy Varnieres]
 - 3DMHD SPH [E. Gouveia del Pino]
 - AMR [Andrew Lim]
 - Nirvana [Udo Ziegler]
 - TD code [Turlough Downes]
 - Hydra [Turlough Downes, Stephen O'Sullivan] Multi-Fluid MHD code
 - Flash [Chicago]

- Codes part 2
 - Gorgon (Resistive MHD, on a fixed 3D eulerian grid, 2 Temp + Q, LTE<Z> +Px), 2nd order hydro
 - Yguazu [Dublin, Raga + De Colle]
 - HyRas 3D hydro rad, cart/cyl/sph. euler, implicit solver
 - RAMSES, AMR HD multi-material gravity chemistry (CEA)(AMR + hydro + multi-Z EOS+ Chemistry)
 - Astrolabe 1D Radiative, multi-fluid, chemistry, gravity (CEA)(1D, hydro.rad, ALE multi-fluid (2 species and 2 temp.)
 - MULTI at Obspm
 - HR, 1 to 3D Eulerian cartesian (can be cylindrical or spheric),
 - grey (Rosseland) eulerian, implicit solver for R-T, gray with moments
 - Belenos (Sebastien Leygnac) 3D stationary Radiative Transfer(Exact 3D solution of radiative transfer equation) [DIAS-Cosmogrid]

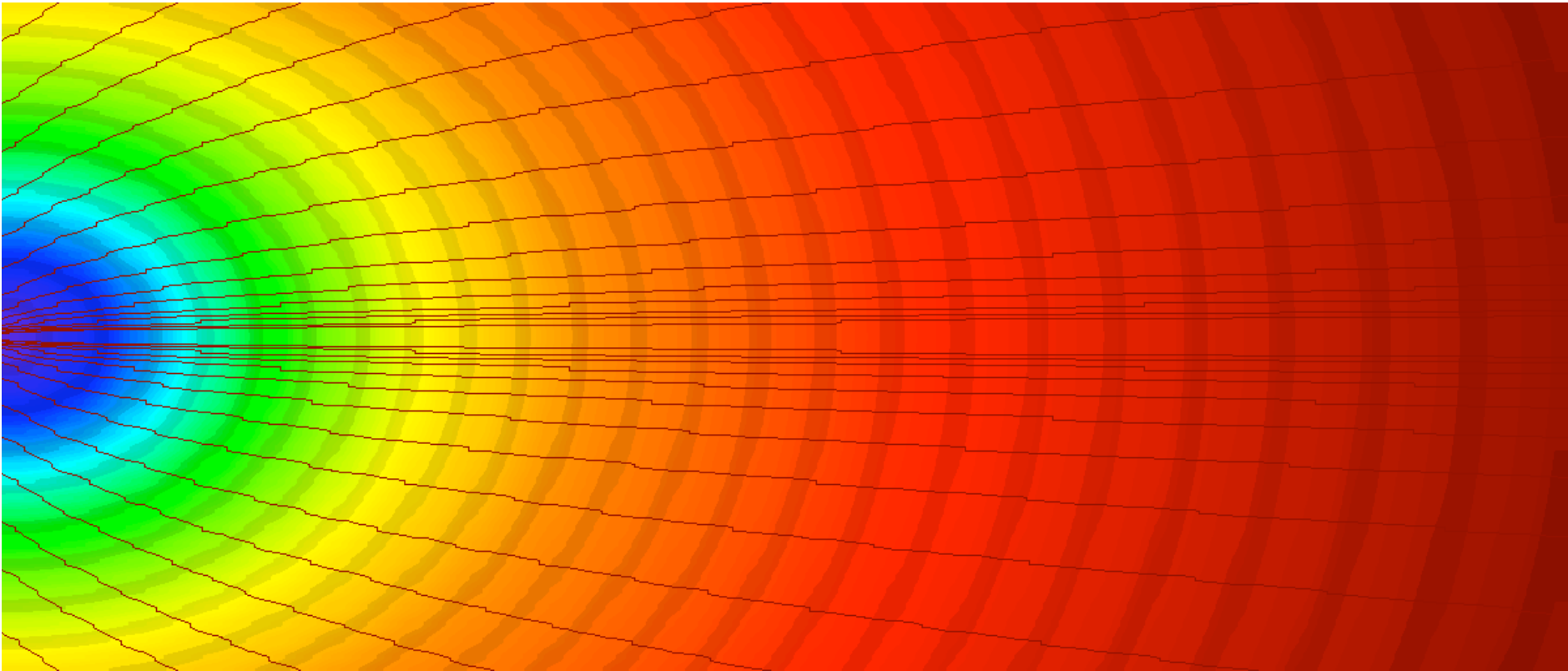
- **Visualisation AND computing**
 - IDL
 - Matlab
 - Mathematica
- **Visualisation only**
 - SuperMongo
 - Gnuplot
 - OpenDX

- “Movies”=animation of the simulations results
 - animated .gifs or .MPEGs
 - propagation of the jet

- Numerical simulation of jet propagation



- Is this physics or “art”?



- **Machines versus codes:**
 - faster machines
 - full 3D
 - larger computational boxes
 - comparisons of the results with the different codes
- **New approaches in coding, new numerical methods**
 - new numerical methods
 - “brutal force” or inovations? BOTH!

- What we can simulate today?

